

# Composing Secure Compilers

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## 1 Introduction

Compilers translate programs from a source to a target programming language. A secure compiler preserves source level properties at the target level when interoperating with arbitrary program contexts (which are considered attackers). A recent theory of secure compilation is Robust Compilation (RC), which is a collection of criteria for secure compilers [1, 2, 13]. Informally, a compiler is RC if a source program and its compiled counterpart, linked with an arbitrary source and target context respectively, satisfy that property.

Even though there exist robust compilers, they are far from practical. Real-world compilers consist of several smaller compilers that are composed with each other in different ways. An example would be any compiler based on the LLVM toolchain [11], whose optimisation pipeline consists of many passes, which one can view as independent compilers composed with each others. Also, any lowering steps, such as from a frontend language to LLVM IR and subsequently to assembly, are compilers. To the best of our knowledge, current work on robust compilation does not discuss the preservation of source-level properties for compilers such as the ones above.

This paper investigates how different compiler compositions preserve different classes of hyperproperties, given that these compilers attain some form of RC. We examine whether these compositions preserve at least the set intersection of classes. We then show that the order of optimisations in a RC pipeline does not matter for property preservation. Finally, we conclude with a discussion on what happens if some compilers in the pipeline do not attain RC for some classes of interest.

## 2 Compositionality

In this work, programs  $p$  are elements of  $\mathcal{P}$ , the set of partial programs of a given programming language. A compiler is a partial function  $\llbracket \bullet \rrbracket^{S \rightarrow T}$  from programs  $p$  of some source language  $S$  to programs  $p$  of some target language  $T$ . Compilers satisfying Definition 2.1 below attain RC [2], the intuition there is that if the programmer makes certain assumptions on what a program does, these assumptions also hold for the compiled program. In that definition, indicate hyperproperties [7] with  $\Pi$  and classes of hyperproperties (i.e., sets of  $\Pi$ ) as  $\mathbb{C}$ . A program  $p$  robustly satisfies class  $\mathbb{C}$  (written  $p \vDash_R \mathbb{C}$ ) if its behaviour is included in an element of  $\mathbb{C}$  when linked with an arbitrary program context. Similarly, for some  $\Pi \in \mathbb{C}$ , we write  $p \vDash_R \Pi$  whenever  $p$  robustly satisfies  $\Pi$ .

**Definition 2.1** (Robust Compilation). For a given class  $\mathbb{C}$ , a compiler from languages  $S$  to  $T$  robustly preserves  $\mathbb{C}$  ( $\vdash \llbracket \bullet \rrbracket^{S \rightarrow T} : \mathbb{C}$ ) iff

$$\forall \Pi \in \mathbb{C}, \forall p \in \mathcal{P}, p \vDash_R \Pi \implies \llbracket p \rrbracket^{S \rightarrow T} \vDash_R \Pi$$

In practice, (robust) compilers are composed of numerous others. Therefore, we now investigate their compositionality.

### 2.1 Simple Compositionality

We first consider function composition, i.e., plugging the result of one compiler into another one. Such pipelines happen when optimising source code (so, at the level of a suitable intermediate representation), but also on a higher level: Consider as an example a typical `TypeScript` compilation pipeline. First, the compiler translates `TypeScript` code to `JavaScript`, which a part of V8 eventually compiles the code just-in-time to `assembly`.

**Definition 2.2** (Sequential Composition of Compilers). Given two compilers  $\llbracket \bullet \rrbracket^{S \rightarrow I}$  and  $\llbracket \bullet \rrbracket^{I \rightarrow T}$ , their sequential composition is  $\llbracket \bullet \rrbracket^{S \rightarrow T} = \llbracket \llbracket \bullet \rrbracket^{S \rightarrow I} \rrbracket^{I \rightarrow T}$ .

Assuming that two compilers preserve certain classes, their sequential composition preserves the least upper bound, i.e., the set intersection of those classes:

**Lemma 2.3** (Sequential Composition with RC). Given  $\vdash \llbracket \bullet \rrbracket^{S \rightarrow I} : \mathbb{C}_1$  and  $\vdash \llbracket \bullet \rrbracket^{I \rightarrow T} : \mathbb{C}_2$ , then  $\vdash \llbracket \bullet \rrbracket^{S \rightarrow I \rightarrow T} : \mathbb{C}_1 \cap \mathbb{C}_2$ .

Using an inductive argument, Lemma 2.3 generalises to  $n$  RC compilers, each preserving one of  $n$  classes. To do so, one has to generalise the composition of two RC compilers to a set of  $n$  ones. A real-world example for such deeply nested compositions is the `TypeScript` compilation mentioned above. When compiling `JavaScript`, V8 translates the code to `Ignition Bytecode`. At runtime, the Ignition interpreter does some performance measurements and particular parts of the code are eventually compiled to machine code.

We now consider a compiler that invokes two other compilers. `Java` and `Kotlin` are popular languages used in industry that are one example of such a composition and they both compile to `JVM Bytecode`.

**Definition 2.4** (Upper Composition). Given two compilers  $\llbracket \bullet \rrbracket^{S \rightarrow T}$  and  $\llbracket \bullet \rrbracket^{I \rightarrow T}$ , their upper composition is

$$\llbracket \bullet \rrbracket^{S+I \rightarrow T} = \lambda p. \begin{cases} \llbracket p \rrbracket^{S \rightarrow T} & \text{if } p \in \mathcal{P} \\ \llbracket p \rrbracket^{I \rightarrow T} & \text{if } p \in \mathcal{P} \end{cases}$$

80 We can derive a similar result to Lemma 2.3 here, too:

81 **Lemma 2.5** (Upper Composition with RC). *Given*  $\vdash [\bullet]^{S \rightarrow T} :$   
 82  $\mathbb{C}_1$  *and*  $\vdash [\bullet]^{I \rightarrow T} : \mathbb{C}_2$ , *then*  $\vdash [\bullet]^{S+I \rightarrow T} : \mathbb{C}_1 \cap \mathbb{C}_2$ .

83 Lemma 2.5 also generalises inductively to a number of  
 84 compilers and classes. A practical example of why that might  
 85 be useful is the Java Virtual Machine with its **JVM Bytecode**,  
 86 which has numerous frontends: **Java**, **Kotlin**, **Scala**, and **Clojure**,  
 87 to list a few examples.

88 With the same idea, we define a dual composition that goes  
 89 from a single source language to multiple target languages.  
 90 **dune** is a build system which can be used to compile **OCaml**  
 91 code to both **assembly** and **Caml Bytecode**.

92 **Definition 2.6** (Lower Composition). *Given two compilers*  
 93  $[\bullet]^{S \rightarrow T}$  *and*  $[\bullet]^{S \rightarrow I}$ , *their lower composition is*  $[\bullet]^{S \rightarrow I+T}$ .

94 **Lemma 2.7** (Lower Composition with RC). *Given*  $\vdash [\bullet]^{S \rightarrow T} :$   
 95  $\mathbb{C}_1$  *and*  $\vdash [\bullet]^{S \rightarrow I} : \mathbb{C}_2$ , *then*  $\vdash [\bullet]^{S \rightarrow I+T} : \mathbb{C}_1 \cap \mathbb{C}_2$ .

96 As before, this can be generalized to an arbitrary number  
 97 of compilers, which also has a connection to the real-world,  
 98 given by the diverse set of assembly language dialects.

99 The following free theorem (Lemma 2.8) is a direct conse-  
 100 quence of Lemma 2.3 where the involved compilers' input  
 101 and output are both partial programs in the same language.  
 102 Given that some compiler passes attain RC, they can be com-  
 103 bined in an arbitrary order and the result preserves the same  
 104 least upper bound. A compiler's pipeline ordering is difficult  
 105 and often hand-tuned. The lemma allows us to not care about  
 106 the particular order of optimisations regarding their robust  
 107 property preservation. So, the compiler developer is free to  
 108 swap passes around.

109 **Lemma 2.8** (Swappable). *Given*  $\vdash [\bullet]_{(1)}^{T \rightarrow T} : \mathbb{C}_1$  *and*  $\vdash [\bullet]_{(2)}^{T \rightarrow T} :$   
 110  $\mathbb{C}_2$ , *then*  $\vdash [[\bullet]_{(2)}^{T \rightarrow T}]_{(1)}^{T \rightarrow T} : \mathbb{C}_1 \cap \mathbb{C}_2$  *and*  $\vdash [[\bullet]_{(1)}^{T \rightarrow T}]_{(2)}^{T \rightarrow T} :$   
 111  $\mathbb{C}_1 \cap \mathbb{C}_2$ .

112 However, in practice, compiler passes are not necessar-  
 113 ily attaining RC. Consider any stereotypical compilation  
 114 pipeline. Programmers want properties at the source level  
 115 to be preserved at the target level. Thus, if source programs  
 116 robustly satisfy some property, so should their compiled  
 117 counterparts. Unfortunately, it might not be necessary for  
 118 compilation passes from one intermediate representation  
 119 to the other to preserve properties robustly. This also has  
 120 a security justification since compiler intermediate repre-  
 121 sentations are not where typical attackers reside (i.e., the  
 122 target language). So, there might be some stronger property  
 123 a pass has to satisfy in order to render the whole compilation  
 124 pipeline secure: this is what we study next.

## 125 2.2 Advanced Compositionality

126 Consider the following C code snippet that performs an  
 127 infinite loop if an invalid pointer is given:

```
128 int something(int* ptr) {
129     while(! ptr);
130     return * ptr;
131 }
```

132 Compiling such code with optimisations turned on by using  
 133 the command `g++ -O2` and the `g++` compiler version 11.2  
 134 yields an x86-program where the potentially infinite loop  
 135 has been removed:

```
136 something(int*):
137     mov eax, DWORD PTR [rdi]
138     ret
```

139 We now have an attack to violate memory safety: call the  
 140 function with an invalid pointer and the program dereferen-  
 141 ces it.

142 To prevent such issues we can use instrumentation passes  
 143 that *enforce* memory safety by adding dynamic checks to the  
 144 program and crashing appropriately when a violation is de-  
 145 tected. There exist several memory-safety instrumentations,  
 146 both for target [8, 15–19] and source languages [3, 12, 14].

147 We now sketch how to extend our work with instrumen-  
 148 tations, which enforce specific classes of hyperproperties.

149 **Definition 2.9** (Secure Instrumentation for Preserving  $\mathbb{C}$ ).  
 150 A secure instrumentation with respect to some class  $\mathbb{C}$  is a  
 151 pass that enforces hyperproperties described by some other  
 152 class  $\mathbb{C}'$  without violating  $\mathbb{C}$ -satisfying programs. We denote  
 153 such a secure instrumentation as:  $[\bullet]^{S \rightarrow T} >_{\mathbb{C}} \mathbb{C}'$ .

154 Using this, we firstly want to inspect a compilation pipeline  
 155 from memory-safe **Rust** to optimised, insecure  $\mathbb{C}$ , to memory-  
 156 safe **CheckedC**. Intuitively, we want to be able to state that  
 157 this pipeline preserves memory safety, despite the fact that  
 158 the pass to  $\mathbb{C}$  does not.

159 **Example 2.10** (Enforcement may preserve...). *Given classes*  
 160  $\mathbb{C}_1, \mathbb{C}_2$  (resp. no property and memory safety, in our **Rust** to  
 161 **CheckedC** example) and compilers  $[\bullet]^{S \rightarrow I}, [\bullet]^{I \rightarrow T}$ , if:

- 162 •  $\vdash [\bullet]^{S \rightarrow I} : \mathbb{C}_1$
- 163 •  $[\bullet]^{I \rightarrow T} >_{\mathbb{C}_1} \mathbb{C}_2$

164 Then,  $\vdash [\bullet]^{S \rightarrow I \rightarrow T} : \mathbb{C}_1 \cup \mathbb{C}_2$ .

165 Dually, running a compiler that does not respect memory-  
 166 safety after a memory-safety instrumentation nullifies its  
 167 preservation:

168 **Example 2.11** (...but, order matters!). *Given classes*  $\mathbb{C}_1, \mathbb{C}_2$   
 169 *and compilers*  $[\bullet]^{S \rightarrow I}, [\bullet]^{I \rightarrow T}$ , if:

- 170 •  $[\bullet]^{S \rightarrow I} >_{\mathbb{C}_1} \mathbb{C}_2$
- 171 •  $\vdash [\bullet]^{I \rightarrow T} : \mathbb{C}_1$

172 Then,  $\vdash [\bullet]^{S \rightarrow I \rightarrow T} : \mathbb{C}_1$ .

173 Beyond this general theory, we also intend to study the  
 174 compositionality aspects of concrete hyperproperties, such  
 175 as Speculative Non-Interference [10], memory safety [4, 5, 9],  
 176 and cryptographic constant-time [6].

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